

1.28inch 4-line-SPI IPS Module MSP1281 User Manual

Product Description

This product is a 1.28-inch round IPS display module, it has a resolution of 240x240. It uses a 4-wire SPI communication method and the inner IC is GC9A01. The module contains an LCD display and PCB backboard.

Product Features

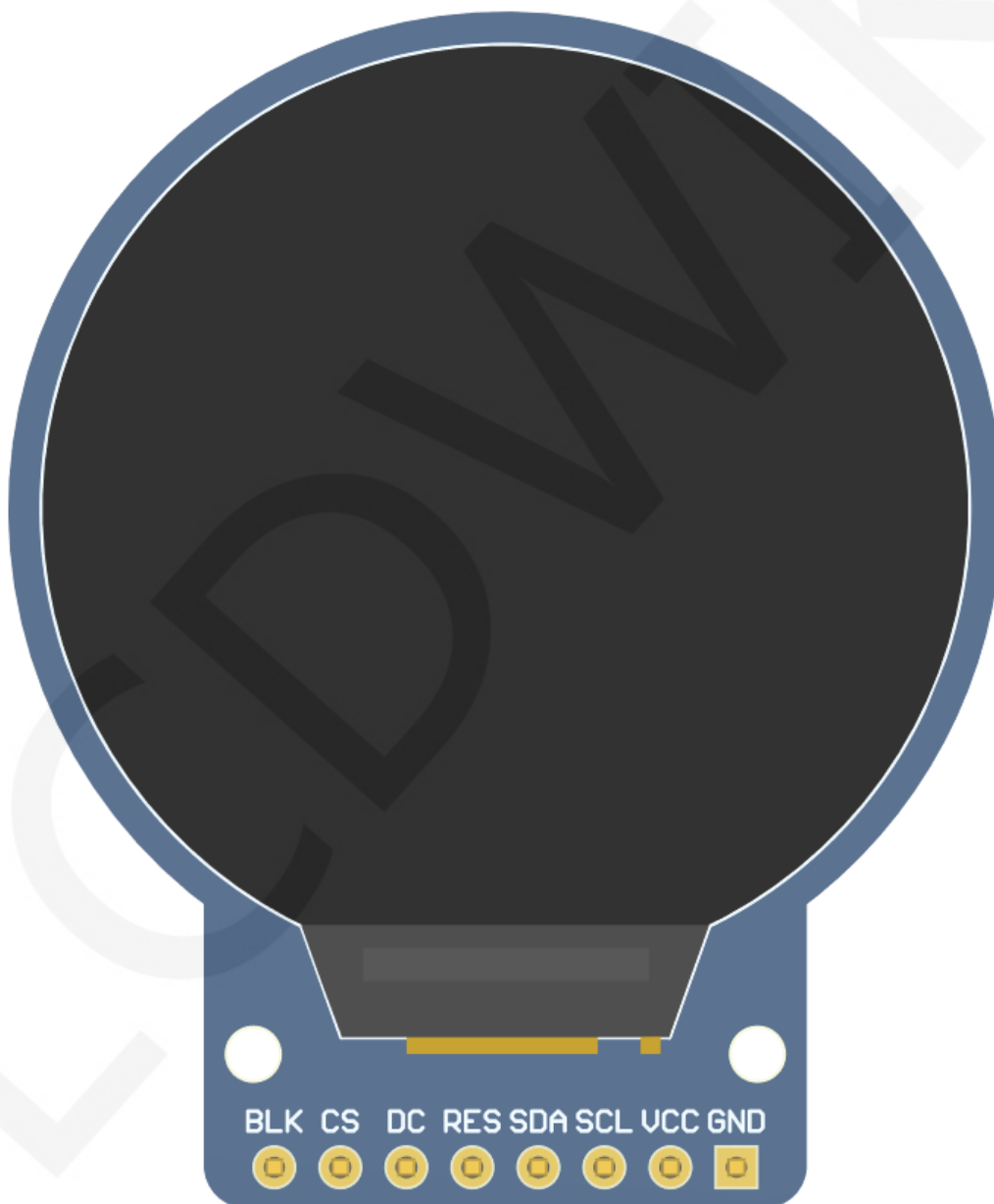
- 1.28-inch round IPS color screen, support 65K color display, display rich colors
- 240X240 resolution, clear display
- Large viewing angle (full angle), display color undistorted.
- Using the 4-line-SPI serial bus, it only takes a few IOs to illuminate the display
- Provide a rich Arduino, STM32, C51 and MSP430 sample program
- Military-grade process standards, long-term stable work
- Provide underlying driver technical support

Product Parameters

Name	Description
Display Color	RGB 65K color
SKU	MSP1281
Screen Size	1.28(inch)
Type	TFT
Driver IC	GC9A01
Resolution	240*240 (Pixel)
Module Interface	4-line SPI interface
Active Area	Diameter: 32.40 (mm)
Touch Screen Type	have no touch screen
Touch IC	have no touch IC
Module PCB Size	38.03x45.80(mm)

Angle of view	all angle
Operating Temperature	-10°C~60°C
Storage Temperature	-20°C~70°C
Operating Voltage	3.3V
Power Consumption	TBD
Product Weight(With packaging)	11(g)

Interface Description



Picture1. Module pin Label picture

important:

1. The following pin numbers 1~8 refer to the module pin numbers of our company with PCB backplane. If you are buying a bare screen, please refer to the pin definition of the bare screen specification, refer to the wiring according to the signal type instead of directly according to the following. The module pin number is used for wiring. For example: DC is 6 feet on our module. It may be x pin on different size bare screen.
2. About VCC supply voltage: The IPS display module can be connected to 3.3V or 5V.
3. About backlight voltage: The module with PCB backplane has integrated triode backlight control circuit, only need to input high level or PWM wave on BL pin to backlight. If you are buying a bare screen, the LEDAx is connected to 3.0V-3.3V, and the LEDKx can be grounded.

Number	Module Pin	Pin Description
1	GND	LCD Power ground
2	VCC	LCD power supply is positive (3.3/5V)
3	SCL	LCD SPI bus clock signal
4	SDA	LCD SPI bus write data signal
5	RES	LCD reset control signal(Low level reset, The module has a reset circuit, and this pin can not be connected)
6	DC	LCD register / data selection control signal(Low level: register, high level: data)
7	CS	LCD chip select control signal (low level enable)
8	BLK	LCD backlight control signal (high level lighting, if you do not need control, please connect 3.3V)

Hardware Configuration

The hardware circuit of the LCD module includes five parts: FPC interface circuit, 3.3V voltage stabilizing circuit, backlight control circuit, pin array interface, and reset circuit.

FPC interface circuit is used to connect bare screen.

3.3V voltage stabilizing circuit is used to stabilize 3.3V output voltage.

The backlight control circuit is used to control the backlight and extinguishment. If the backlight is not required. It can be connected to 3.3V power supply.

The pin array interface is used to connect various development boards.

The reset circuit is used for module power on reset.

working principle

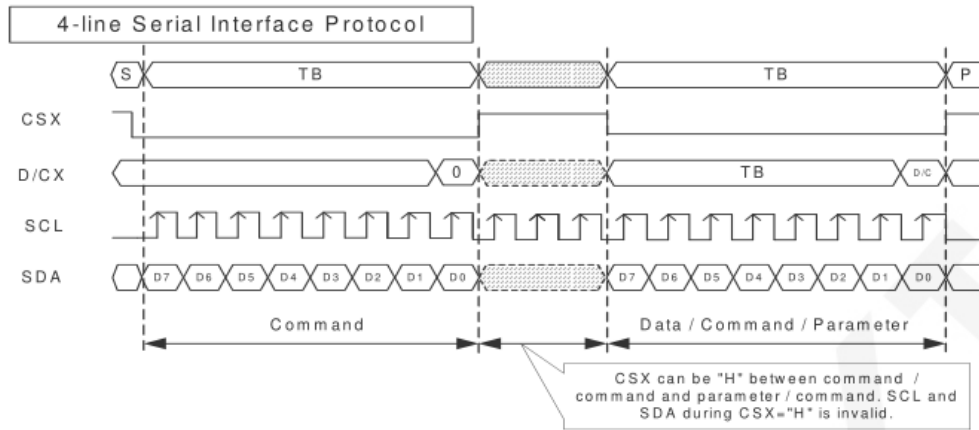
1. Introduction to GC9A01 Controller

The GC9A01 controller supports a maximum resolution of 240*240 and a 129600-byte GRAM. It also supports 8-bit, 9-bit, 12-bit, 16-bit, and 18-bit parallel port data buses. It also supports 3-wire and 4-wire SPI serial ports. Since parallel control requires a large number of IO ports, the most common one is SPI serial port control. The GC9A01 also supports 65K, 262K RGB color display, display color is very rich, while supporting rotating display and scroll display and video playback, display in a variety of ways.

The GC9A01 controller uses 16bit (RGB565) to control a pixel display, so it can display up to 65K colors per pixel. The pixel address setting is performed in the order of rows and columns, and the incrementing and decreasing direction is determined by the scanning mode. The GC9A01 display method is performed by setting the address and then setting the color value.

2. Introduction to SPI communication protocol

The 4-wire SPI bus write mode timing is shown in the following figure:



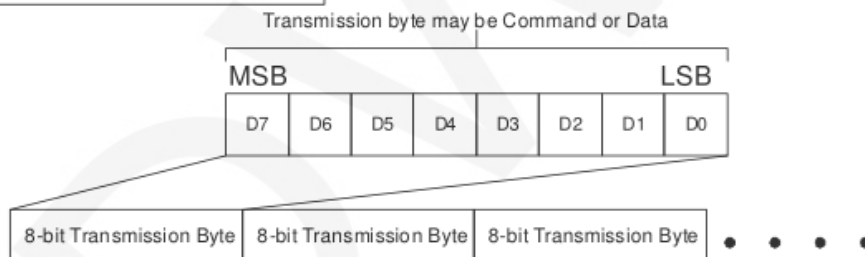
CSX is a slave chip select, and the chip is enabled only when CSX is low.

D/CX is the data/command control pin of the chip. When DCX is low, the command is written. When it is high, the data is written.

SCL is the SPI bus clock, and each rising edge transmits 1 bit of data;

SDA is the data transmitted by SPI, and it transmits 8-bit data at a time. The data format is as shown below:

Data Format for 4-line Serial Interface



The high position is in front and transmitted first.

For SPI communication, the data has a transmission timing, that is, a combination of clock phase (CPHA) and clock polarity (CPOL):

The CPOL level determines the idle state level of the serial synchronous clock, CPOL = 0, which is low. CPOL does not have a lot of impact on the transport protocol;

The level of CPHA determines whether the serial synchronous clock is acquired on the first clock transition edge or the second clock transition edge.

When CPHL = 0, data acquisition is performed on the first edge of the transition;

The combination of the two becomes the four SPI communication methods. SPI0 is usually used in China, that is, CPHL = 0, CPOL = 0.

Instructions for use

1. STM32 instructions

Wiring instructions:

See the interface description for pin assignments.

STM32F103C8T6 microcontroller test program wiring instructions		
Number	Module Pin	Corresponding to MiniSTM32 development board wiring pin
1	GND	GND
2	VCC	3.3V/5V
3	SCL	PA5
4	SDA	PA7
5	RES	PB8
6	DC	PB7
7	CS	PB9
8	BLK	PB6

STM32F103RCT6 microcontroller test program wiring instructions		
Number	Module Pin	Corresponding to MiniSTM32 development board wiring pin
1	GND	GND
2	VCC	3.3V/5V
3	SCL	PB13
4	SDA	PB15
5	RES	PB12
6	DC	PB10
7	CS	PB11
8	BLK	PB9

STM32F103ZET6 microcontroller test program wiring instructions

Number	Module Pin	Corresponding to Elite STM32 development board wiring pin
1	GND	GND
2	VCC	3.3V/5V
3	SCL	PB13
4	SDA	PB15
5	RES	PB12
6	DC	PB10
7	CS	PB11
8	BLK	PB9

STM32F407ZGT6 microcontroller test program wiring instructions

Number	Module Pin	Corresponding to Explorer STM32F4 development board wiring pin
1	GND	GND
2	VCC	3.3V/5V
3	SCL	PB3
4	SDA	PB5
5	RES	PB12
6	DC	PB14
7	CS	PB15
8	BLK	PB13

STM32F429IGT6 microcontroller test program wiring instructions		
Number	Module Pin	Corresponding to Apollo STM32F4/F7 development board wiring pin
1	GND	GND
2	VCC	3.3V/5V
3	SCL	PF7
4	SDA	PF9
5	RES	PD12
6	DC	PD5
7	CS	PD11
8	BLK	PD6

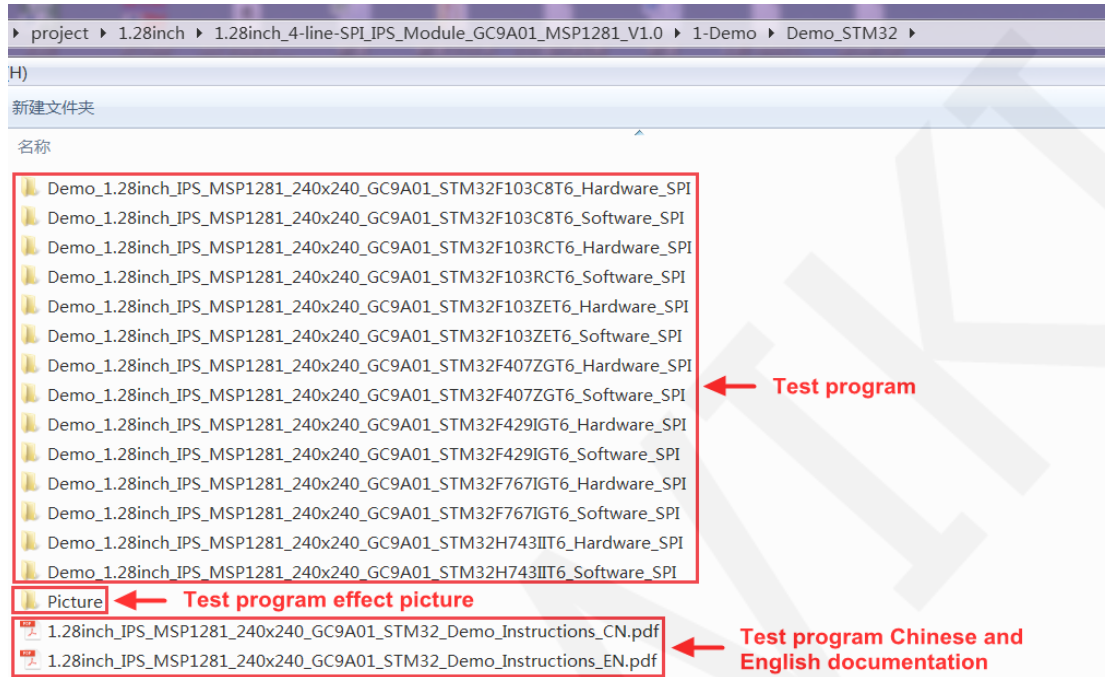
STM32F767IGT6 and STM32H743IIT6 microcontroller test program wiring instructions		
Number	Module Pin	Corresponding to Apollo STM32F4/F7 development board wiring pin
1	GND	GND
2	VCC	3.3V/5V
3	SCL	PB13
4	SDA	PB15
5	RES	PD12
6	DC	PD5
7	CS	PD11
8	BLK	PD6

Operating Steps:

- A. Connect the IPS module and the STM32 MCU according to the above wiring instructions, and power on;
- B. Select the test example according to the model of the microcontroller, as shown

in the following figure:

(Please refer to the test program description document in the test package for the test program description)



C. Open the selected test program project, compile and download;

detailed description of the STM32 test program compilation and download can be found in the following document:

http://www.lcdwiki.com/res/PublicFile/STM32_Keil_Use_Illustration_EN.pdf

D. If the IPS module displays characters and graphics normally, the program runs successfully;

2. C51 instructions

Wiring instructions:

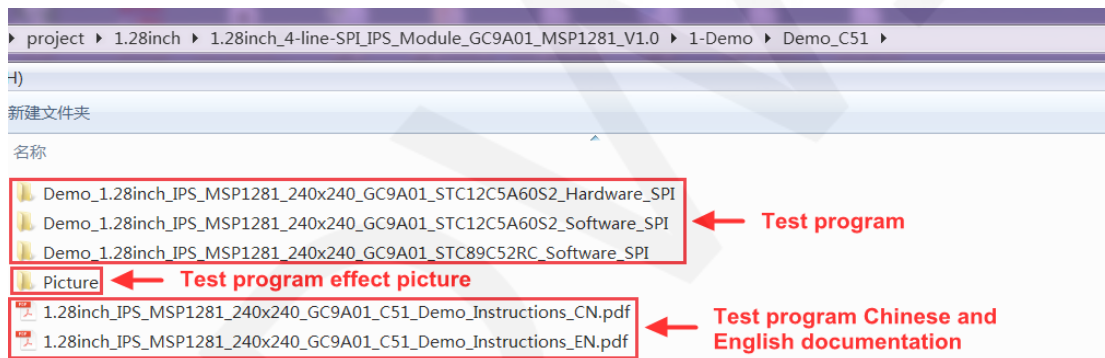
See the interface description for pin assignments.

STC89C52RC and STC12C5A60S2 microcontroller test program wiring instructions		
Number	Module Pin	Corresponding to STC89/STC12 development board wiring pin
1	GND	GND
2	VCC	3.3V/5V

3	SCL	P17
4	SDA	P15
5	RES	P33
6	DC	P12
7	CS	P13
8	BLK	P32

Operating Steps:

- A. Connect the IPS module and the C51 MCU according to the above wiring instructions, and power on;
- B. Select the C51 test program to be tested, as shown below:
(Please refer to the test program description document in the test package for the test program description)



- C. Open the selected test program project, compile and download;
detailed description of the C51 test program compilation and download can be found in the following document:
http://www.lcdwiki.com/res/PublicFile/C51_Keil%26stc-isp_Use_Illustration_EN.pdf
- D. If the IPS module displays characters and graphics normally, the program runs successfully;

3. Arduino instructions

Wiring instructions:

Arduino UNO microcontroller test program wiring

Number	Module Pin	Corresponding to UNO development board wiring pins
1	GND	GND
2	VCC	3.3V/5V
3	SCL	13
4	SDA	11
5	RES	A4
6	DC	A3
7	CS	A2
8	BLK	A0

Arduino MEGA2560 microcontroller test program wiring

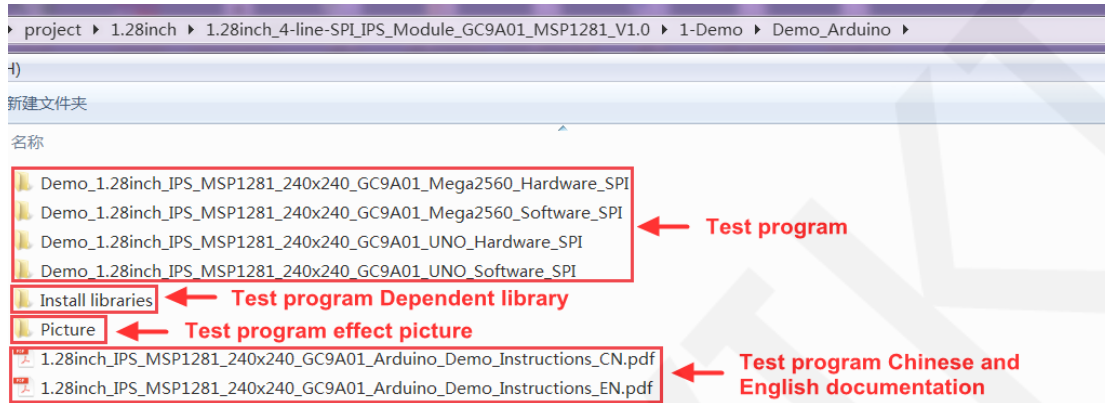
Number	Module Pin	Corresponding to MEGA2560 development board wiring pins
1	GND	GND
2	VCC	3.3V/5V
3	SCL	52
4	SDA	51
5	RES	A4
6	DC	A3
7	CS	A2
8	BLK	A0

Operating Steps:

- A. Connect the LCD module and the Arduino MCU according to the above wiring instructions, and power on;
- B. Copy the dependent libraries in the Install libraries directory of the test package to the libraries folder of the Arduino project directory (the default Arduino project directory is C:\Users\Administrator\Documents\Arduino\libraries.if you do not need to depend on the libraries, you do not need to copy them);

- C. Open the directory where the Arduino test program is located and select the example you want to test, as shown below:

(Please refer to the test program description document in the test package for the test program description)



- D. Open the selected sample project, compile and download.

The specific operation methods for the Arduino test program relying on library copy, compile and download are as follows:

http://www.lcdwiki.com/res/PublicFile/Arduino_IDE_Use_Illustration_EN.pdf

- E. If the LCD module displays characters and graphics normally, the program runs successfully;

4. MSP430 instructions

Wiring instructions:

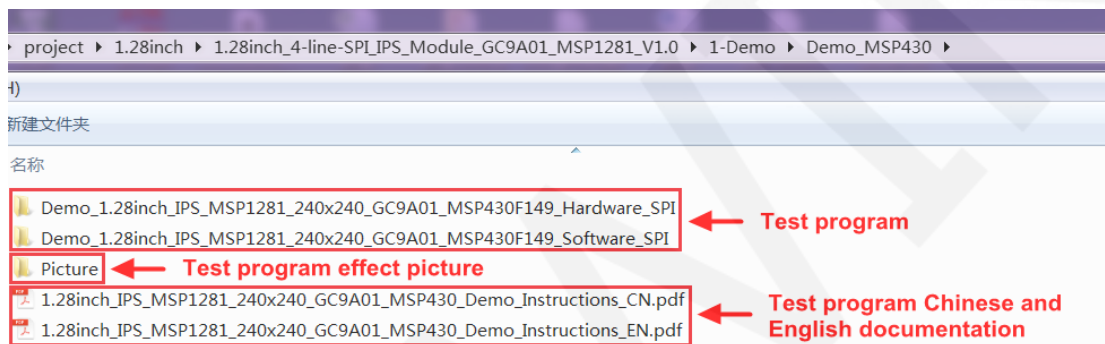
See the interface description for pin assignments.

MSP430F149 microcontroller test program wiring instructions		
Number	Module Pin	Corresponding to MSP430 development board wiring pin
1	GND	GND
2	VCC	3.3V/5V
3	SCL	P33
4	SDA	P31
5	RES	P22
6	DC	P21

7	CS	P23
8	BLK	P20

Operating Steps:

- A. Connect the IPS module and the MSP430 MCU according to the above wiring instructions, and power on;
- B. Select the MSP430 test program to be tested, as shown below:
(Please refer to the test program description document in the test package for the test program description)



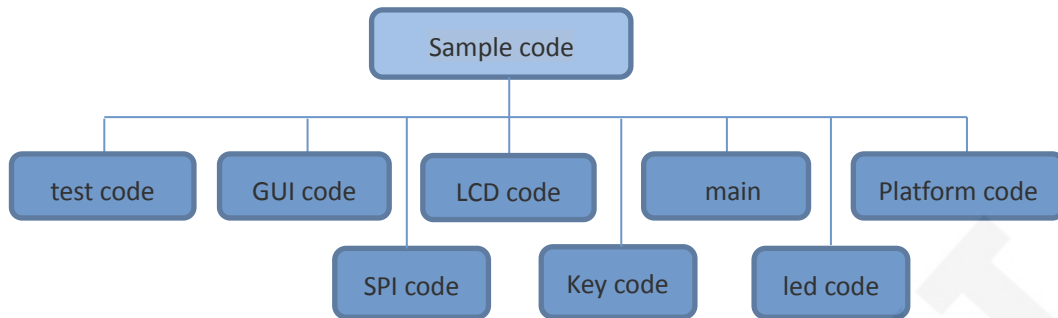
- C. Open the selected test program project, compile and download;
detailed description of the MSP430 test program compilation and download can be found in the following document:
http://www.lcdwiki.com/res/PublicFile/IAR_IDE%26MspFet_Use_Illustration_EN.pdf
- D. If the IPS module displays characters and graphics normally, the program runs successfully;

Software Description

1. Code Architecture

A. C51, STM32 and MSP430 code architecture description

The code architecture is shown below:



The Demo API code of the main program runtime is included in the test code;

LCD initialization and related operations are included in the LCD code;

Drawing points, lines, graphics, and Chinese and English character display related operations are included in the GUI code;

The main function implements the application to run;

Platform code varies by platform;

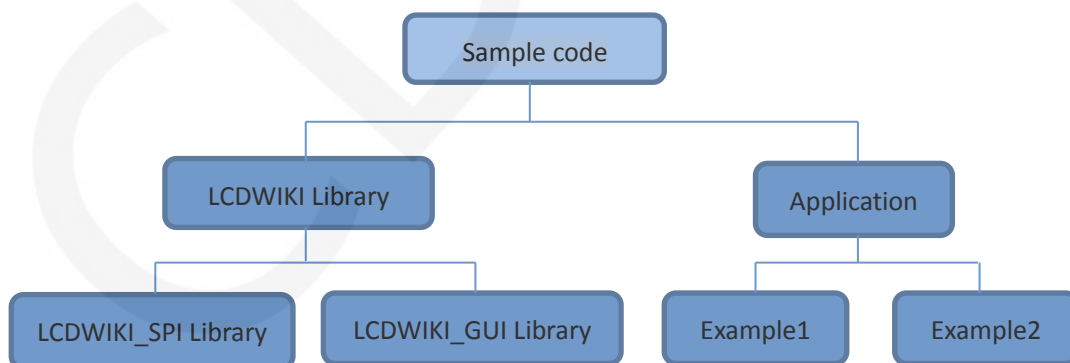
SPI initialization and configuration related operations are included in the SPI code;

The key processing related code is included in the key code (the C51 and MSP 430 platform does not have a button processing code);

The code related to the led configuration operation is included in the led code(the MSP 430 platform does not have a led code);

B. Arduino code architecture description

The code architecture is shown below:



Arduino's test program code consists of two parts: the LCDWIKI library and application code.

The LCDWIKI library consists of two parts: the LCDWIKI_SPI library and the

LCDWIKI_GUI library.

The application contains several test examples, each of which contains different test content.

LCDWIKI_SPI is the underlying library, which is associated with hardware. It is mainly responsible for operating registers, including hardware module initialization, data and command transmission, pixel coordinates and color settings, and display mode configuration.

LCDWIKI_GUI is a middle-tier library, which is responsible for drawing graphics and displaying characters using the API provided by the underlying library.

The application uses the API provided by the LCDWIKI library to write some test examples to implement some aspects of the test function.

2. software SPI and hardware SPI description

The IPS module provides software SPI and hardware SPI sample code (except STC89C52RC, because it does not have hardware SPI function), the two sample code does not make any difference in the display content, but the following aspects are different:

A. display speed

The hardware SPI is significantly faster than the software SPI, which is determined by the hardware.

B. GPIO definition

The software SPI all control pins must be defined, any idle pin can be used, the hardware SPI data and clock signal pins are fixed (depending on the platform), other control pins should be defined by themselves, or any idle reference can be used. foot.

C. initialization

When the software SPI is initialized, only the GPIO for pin definition needs to be initialized (not required by the C51 platform). When the hardware SPI is initialized, the relevant control registers and data registers need to be initialized.

3. GPIO definition description

A. STM32 test program GPIO definition description

non-SPI GPIO definition is placed in lcd.h as shown below (take STM32F103RCT6 microcontroller FSMC test program as an example):

```
//-----LCD端口定义-----  
#define GPIO_TYPE  GPIOB //GPIO组类型  
#define LED         9     //背光控制引脚      PB9  
#define LCD_CS      11    //片选引脚          PB11  
#define LCD_RS      10    //寄存器/数据选择引脚 PB10  
#define LCD_RST     12    //复位引脚          PB12
```

All pin definitions can be modified and can be defined as any other free GPIO.

If you are using a hardware SPI test program, you do not need to define the GPIO of the SPI.

If you use the software SPI test program, the SPI GPIO definition is placed in spi.h, as shown below (take STM32F103RCT6 microcontroller test program as an example):

```
#define LCD_CTRL      GPIOB //定义TFT数据端口  
#define SPI_SCLK     GPIO_Pin_13 //PB13--->>TFT --SCL/SCK  
#define SPI_MISO     GPIO_Pin_14  
#define SPI_MOSI     GPIO_Pin_15 //PB15 MOSI--->>TFT --SDA/DIN
```

all pin definitions can be modified and can be defined as any other free GPIO.

B. C51 test program GPIO definition description

GPIO definition is placed in the lcd.h file, as shown below:

```
//Io连接  
sbit LCD_RS = P1^2; //数据/命令切换  
sbit LCD_SDI = P1^5; //SPI写  
sbit LCD_SDO = P1^6; //SPI读  
sbit LCD_CS = P1^3; //片选  
sbit LCD_CLK = P1^7; //SPI时钟  
sbit LCD_RESET = P3^3; //复位  
sbit LCD_BL=P3^2; //背光控制，如果不需要控制，接3.3V
```

If the software SPI is used, all pin definitions can be modified and can be defined as any other free GPIO.

If hardware SPI is used, the LCD_BL, LCD_RS, LCD_CS, and LCD_RST pin definitions can be modified and can be defined as any other free GPIO. LCD_CLK and LCD_SDI do not need to be defined.

C. Arduino test program GPIO definition description

The LCD screen and touch screen GPIO definitions of the Arduino test program are placed separately in each application, which means that each application can flexibly define GPIO according to requirements. As shown below (take UNO software SPI test program as an example):

```
//paramters define
#define MODEL ST7789
#define CS A2
#define CD A3
#define RST A4
#define SDA 11
#define SCK 13
#define LED A0 //if you don't need to control
```

D. MSP430 test program GPIO definition description

non-SPI GPIO definition is placed in lcd.h as shown below:

```
//////////////////////////////////////
//-----LCD端口定义-----
#define LED BIT0 //背光控制引脚 P20
#define LCD_RS BIT1 //寄存器/数据选择引脚 P21
#define LCD_RST BIT2 //复位引脚 P22
```

All pin definitions can be modified and can be defined as any other free GPIO.

If you are using a hardware SPI test program, you do not need to define the GPIO of the SPI.

If you use the software SPI test program, the SPI GPIO definition is placed in spi.h, as shown below:

```
//本测试程序使用的是软件SPI接口驱动
//SPI时钟信号以及SPI读、写信号引脚都可以更改

#define SPI_SCLK BIT3 //P33
#define SPI_MOSI BIT1 //P31
```

all pin definitions can be modified and can be defined as any other free GPIO.

4. SPI communication code implementation

A. STM32 test program SPI communication code implementation

Hardware SPI communication is implemented by the system. We only need to operate the register and call the relevant function. For details, please refer to the MCU related documentation.

The software SPI communication code is implemented in spi.c ,as shown in the following figure:

```
void SPIv_WriteData(u8 Data)
{
    unsigned char i=0;
    for(i=8;i>0;i--)
    {
        if(Data&0x80)
            LCD_SDA_SET; //输出数据
        else
            LCD_SDA_CLR;
        LCD_SCL_CLR;
        LCD_SCL_SET;
        Data<<=1;
    }
}
```

If the transmitted data bit is 1, the SPI data pin is pulled high. When it is 0, the SPI data pin is pulled low, one byte of data is transferred each time, the upper bit is first, and one bit of data is transmitted on each rising edge of the clock.

B. C51 test program SPI communication code implementation

The software SPI communication code is implemented in lcd.c ,as shown in the following figure:

```
void spi_write_byte(u8 d)
{
    u8 val=0x80;
    while(val)
    {
        if(d&val)
        {
            LCD_SDI = 1;
        }
        else
        {
            LCD_SDI = 0;
        }
        LCD_CLK = 0;
        LCD_CLK = 1;
        val>>=1;
    }
}
```

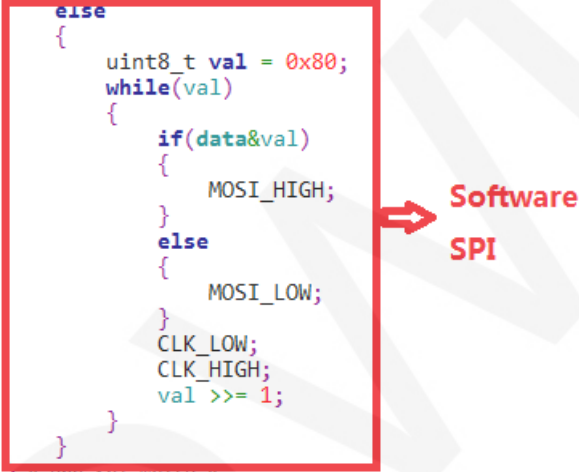
If the transmitted data bit is 1, the SPI data pin is pulled high. When it is 0, the SPI data pin is pulled low, one byte of data is transferred each time, the upper bit is first, and one bit of data is transmitted on each rising edge of the clock.

C. Arduino test program SPI communication code implementation

Hardware SPI communication is implemented by the system. We only need to operate the register and call the relevant function. For details, please refer to the MCU related documentation.

The software SPI communication code is implemented in the LCDWIKI_SPI.cpp file of the LCDWIKI_SPI library, as shown below:

```
//spi write for hardware and software
void LCDWIKI_SPI::Spi_Write(uint8_t data)
{
    if(hw_spi)
    {
        SPI.transfer(data);
    }
    else
    {
        uint8_t val = 0x80;
        while(val)
        {
            if(data&val)
            {
                MOSI_HIGH;
            }
            else
            {
                MOSI_LOW;
            }
            CLK_LOW;
            CLK_HIGH;
            val >>= 1;
        }
    }
}
// end spi_write
```



If the transmitted data bit is 1, the SPI data pin is pulled high. When it is 0, the SPI data pin is pulled low, one byte of data is transferred each time, the upper bit is first, and one bit of data is transmitted on each rising edge of the clock.

D. MSP430 test program SPI communication code implementation

The software SPI communication code is implemented in spi.c ,as shown in the following figure:

```
/******  
 * @name      :void SPI_WriteByte(u8 Data)  
 * @date      :2018-08-09  
 * @function   :Write a byte of data using STM32's hardware SPI  
 * @parameters :SPIx: SPI type,x for 1,2,3  
 *              Byte:Data to be written  
 * @retvalue   :Data received by the bus  
*****/  
void SPI_WriteByte(u8 Data)  
{  
    unsigned char i=0;  
    for(i=8;i>0;i--)  
    {  
        if(Data&0x80)  
            SPI_MOSI_SET; //输出数据  
        else SPI_MOSI_CLR;  
  
        SPI_SCLK_CLR;  
        SPI_SCLK_SET;  
        Data<<=1;  
    }  
}
```

If the transmitted data bit is 1, the SPI data pin is pulled high. When it is 0, the SPI data pin is pulled low, one byte of data is transferred each time, the upper bit is first, and one bit of data is transmitted on each rising edge of the clock.

Common software

This set of test examples requires the display of Chinese and English, symbols and pictures, so the modulo software is used. There are two types of modulo software: Image2Lcd and PctoLCD2002. Here is only the setting of the modulo software for the test program.

The **PctoLCD2002** modulo software settings are as follows:

Dot matrix format select **Dark code**

the modulo mode select **the progressive mode**

Take the model to choose **the direction (high position first)**

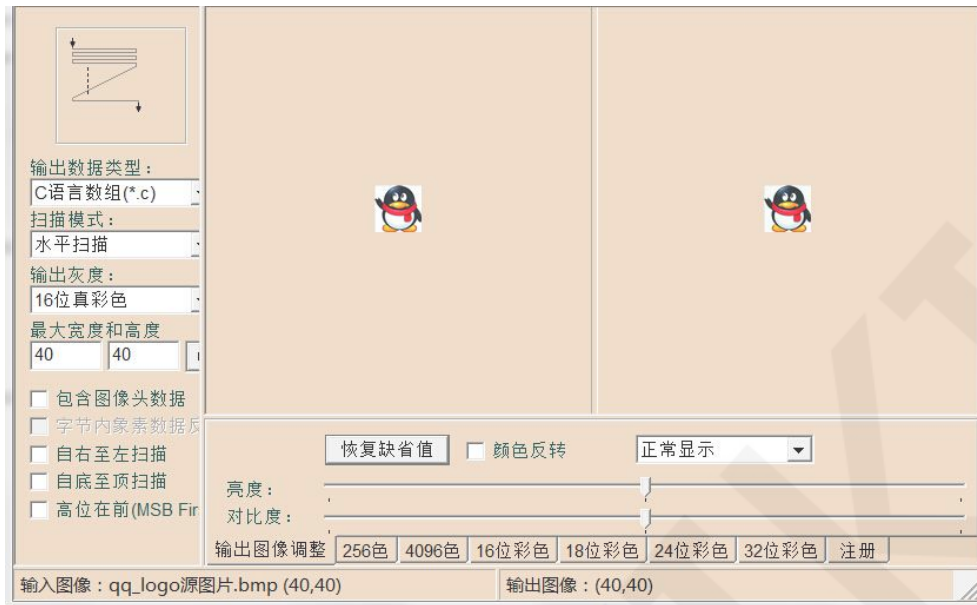
Output number system selects **hexadecimal number**

Custom format selection **C51 format**

The specific setting method is as follows:

http://www.lcdwiki.com/Chinese_and_English_display_modulo_settings

Image2Lcd modulo software settings are shown below:



The Image2Lcd software needs to be set to horizontal, left to right, top to bottom, and low position to the front scan mode.